

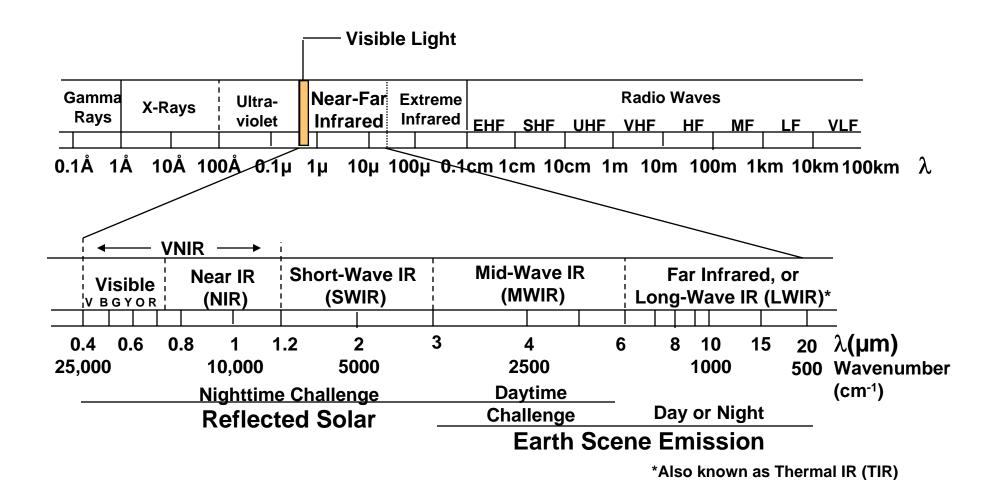
Passive Electro-optical Environmental Imaging

Carl F. Schueler

Presented at Naval Research Laboratory, Monterey CA 14 November 2003

Focus on Visible to Far Infrared

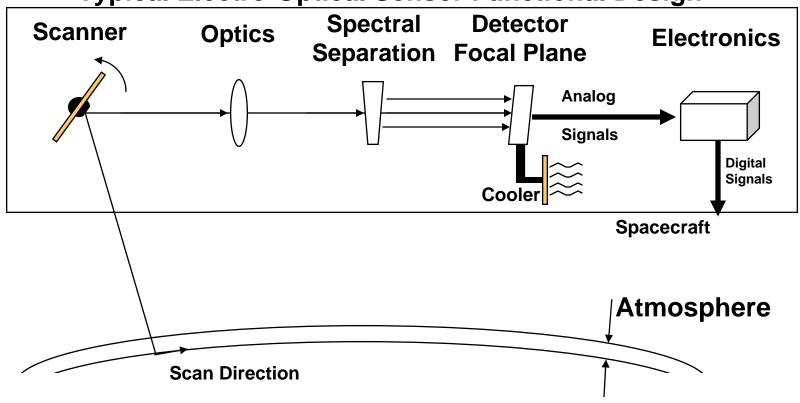




Emitted or Reflected Radiance to Image Data

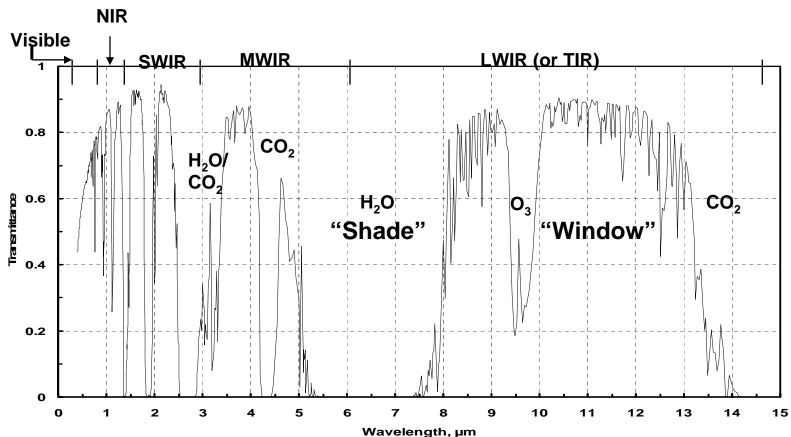


Typical Electro-Optical Sensor Functional Design



Atmosphere "Shades" & "Windows" Guide Spectral Band Selection





- Clear Windows Selected for Surface Features
- Steep "Edges" Excellent for Atmospheric Sensing ("Sounding")
- Transmission Characteristics Caused by Gas Absorption (Main "Culprits" Shown)

Raytheon Santa Barbara Remote Sensing

Topics to be Discussed

- Overview of recent environmental sensors
 - Sea-Viewing Wide Field-of-View Sensor (SeaWiFS) 1993
 - Tropical Rainfall Measuring Mission (TRMM) Visible Infrared Scanner (VIRS) 1997
 - NASA Earth Observing System MODerate-resolution Imaging Spectroradiometer (MODIS) - 1999
 - National Polar-orbiting Operational Environmental Satellite System (NPOESS).
 Visible Infrared Imaging Radiometer Suite (VIIRS) in development
- Methodology to define sensor specification from user needs
- Compare AVHRR/DMSP OLS and VIIRS Spatial Resolution
- Fundamental sensor design issue: Spatial resolution vs. Sensitivity for Feature identification

Sea-viewing Wide Field-ofview Sensor (SeaWiFS)



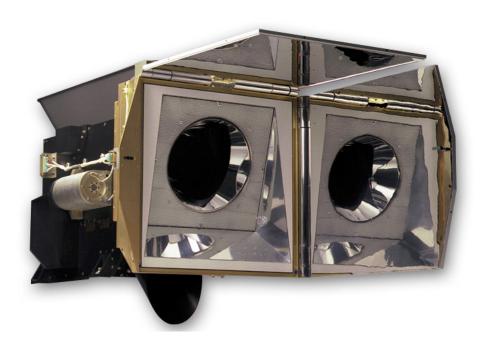
- Delivered December 1993/Launched 4 September 1997
- Orbit: 705km noon polar sun-synchronous
- 1.13 km nadir geometric instantaneous field of view (GIFOV)
- Off-axis, afocal 7.6 cm aperture rotating telescope, focusing aft optics
- 360 rpm telescope cross-track scan
- Sun glint avoidance via commandable +/- 20 degree sensor fore-aft tilt
- 22 kg scanner/24 kg electronics box
- 51 x 51 x 51 cm
- Eight spectral bands 0.4-0.885 um
- 670-950 Signal-to-noise ratio for ocean reflectance measurements
- On-board solar diffuser calibration update reference



Tropical Rainfall Measuring Mission (TRMM) Visible Infrared Scanner (VIRS)



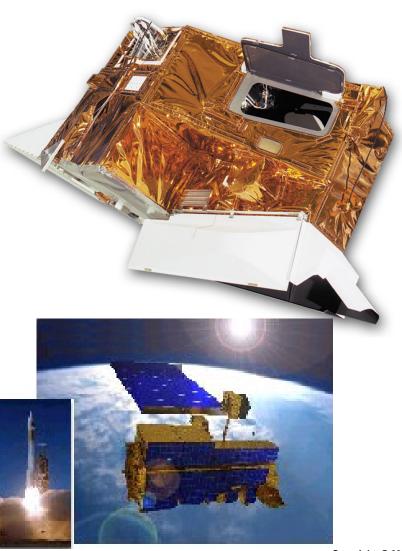
- Launched 27 November 1997
- Orbit: 350km equatorial 35 degree inclination
- 2km nadir GIFOV
- 2-mirror Cassegrain 9 cm aperture telescope
- Cross-track "paddle" scan mirror (similar to MODIS scan design)
- 24 kg scanner/13 kg electronics box
- 43 x 80 x 46 cm scanner dimensions
- 5 (AVHRR) spectral bands 0.63-12 um
- Excellent SNR and NEdT for cloud analyses via passive radiative cooling
- On-board calibration update references:
 - Solar diffuser for reflective bands
 - Blackbody for emissive bands



MODerate-resolution Imaging Spectroradiometer (MODIS)

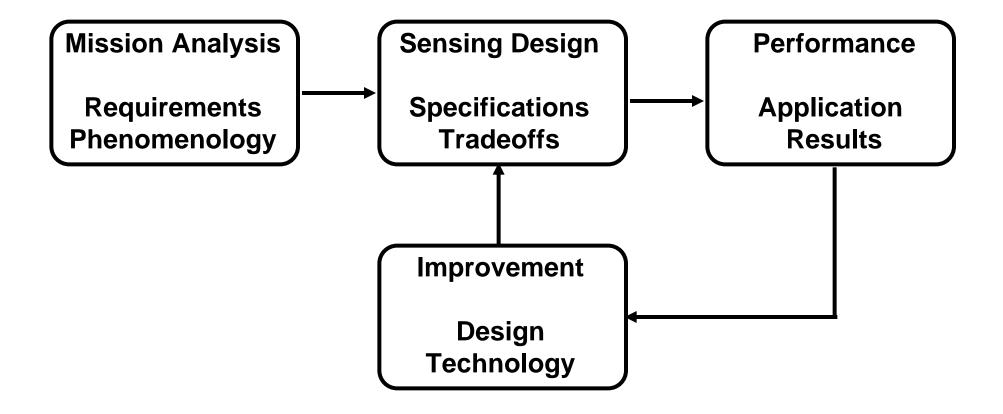


- First launched 18 December 1999 on NASA's EOS Terra spacecraft
- Orbit: 705km polar sun-synchronous 2230 ascending (& Aqua 1330 ascending)
- Nadir GIFOVs: 250m in 2 vis bands; 500m in 5 VNIR bands; 1km in 29 VNIR-LWIR bands
- Off-axis, afocal with intermediate field stop and focusing refractive aft optics
- 20 rpm cross-track "paddle" scan mirror
- 250 kg scanner/electronics package
- 100 x 160 x 100 cm
- Excellent SNR and NEdT for atmosphere, land, and ocean analyses via passive radiative cooling
- On-board calibration update references:
 - Solar diffuser and stability monitor for reflective bands
 - Blackbody for emissive bands
 - Space and lunar views
 - Spectroradiometric calibration assembly for spectral band registration and center updates



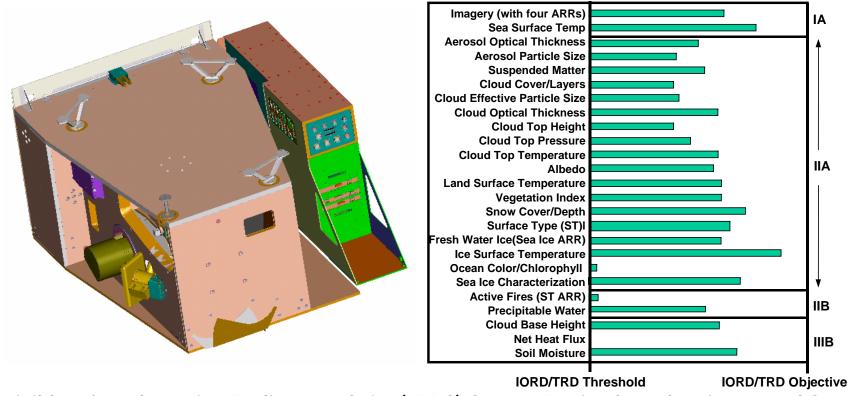
User Needs Drove Design





VIIRS Provides Environmental Data Records (EDRs)

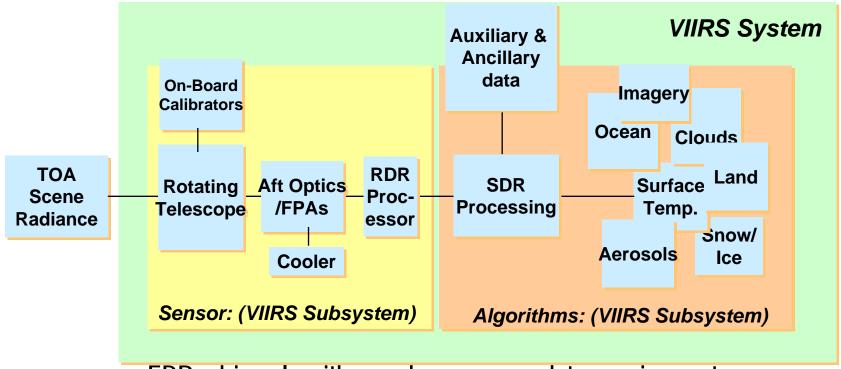




- Visible Infrared Imaging Radiometer Suite (VIIRS) System Design based on integrated Sensor and Algorithms
- Engineering Development Unit (EDU) approaching integration at SBRS
- EDR Science Algorithms developed, documented, and publicly released Spring 2002 by Raytheon Technical Services Company (RTSC) Information Technology and Scientific Services (ITSS)

EDR Performance Verified by Hardware & Testbed

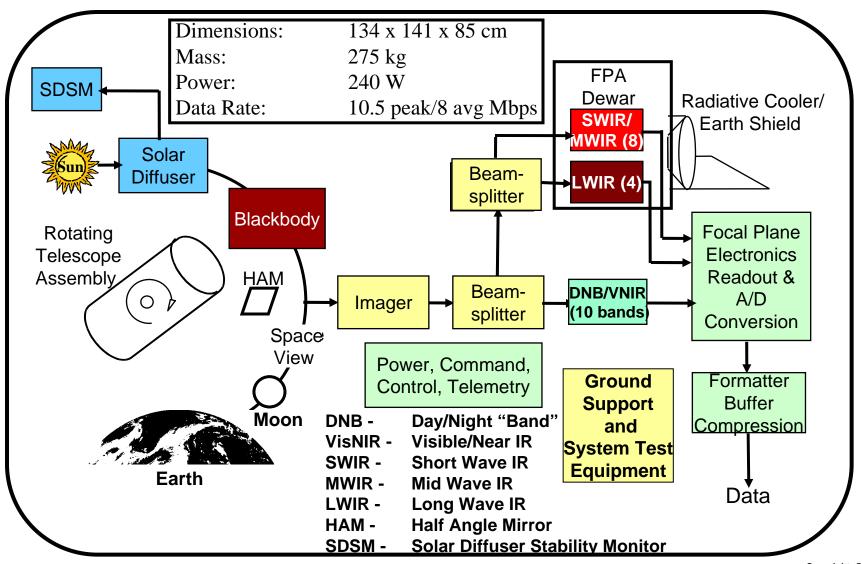




- Closed the Loop!
- EDRs drive algorithm and raw sensor data requirements
- Sensor specification derived from EDRs with testbed
- Sensor performance verified by hardware risk-reduction demonstrations and analyses
- EDR performance verified by testbed with sensor models

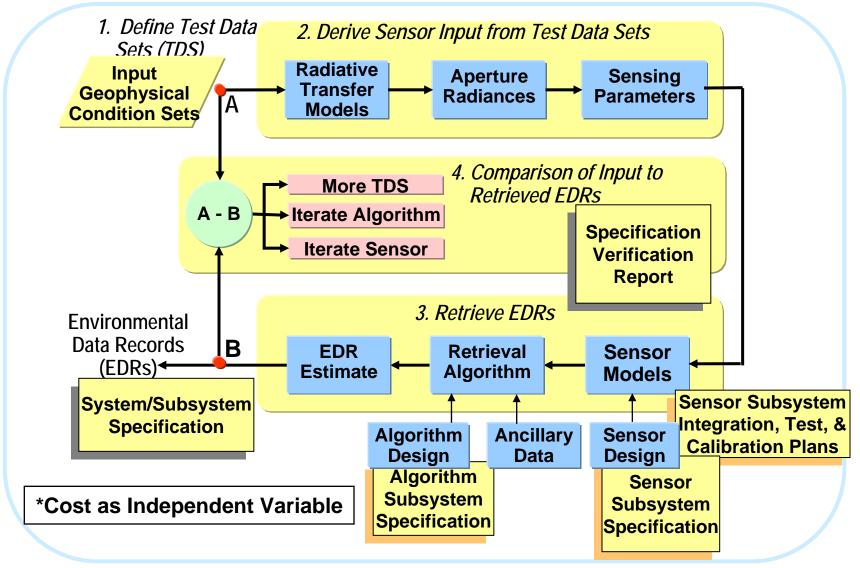
Photons to Digital Data: VIIRS Architecture Stable Since PDR





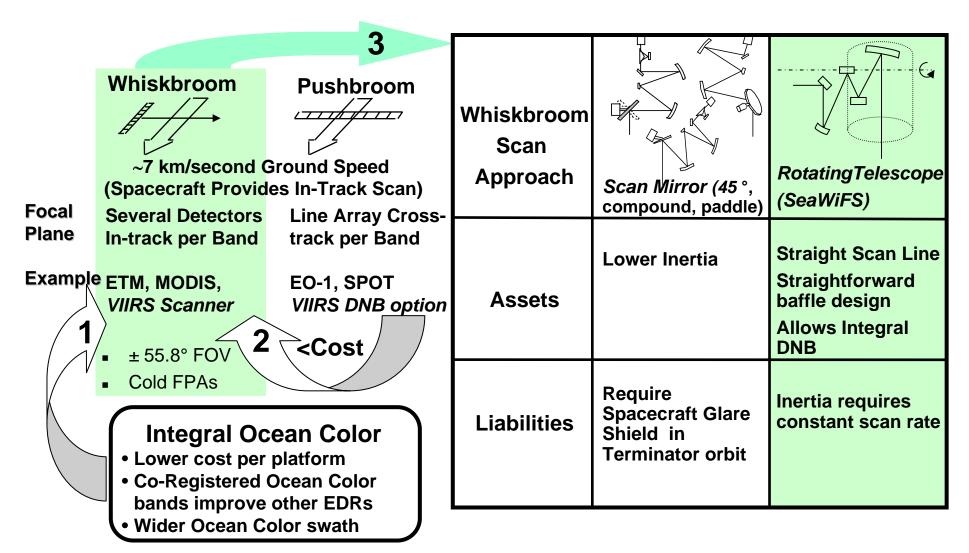
Testbed-based CAIV* Trades For "Best Value" Optimization





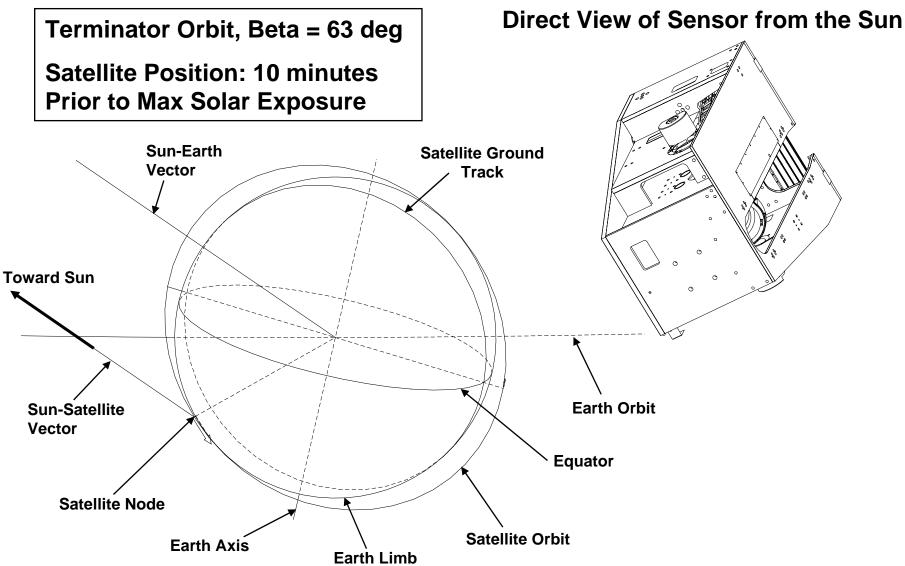
CAIV Trades For Best Value Single Sensor Configuration





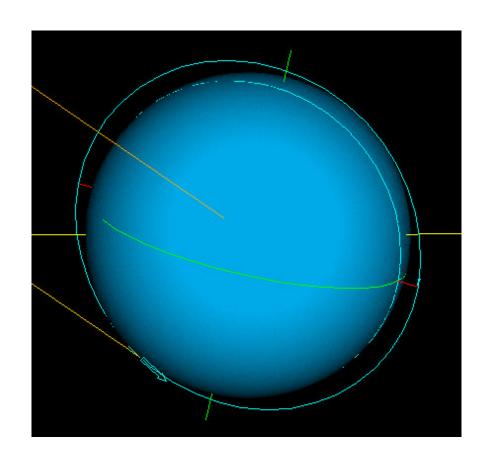
Solar intrusion in Terminator orbit: Rotating Telescope Design Driver

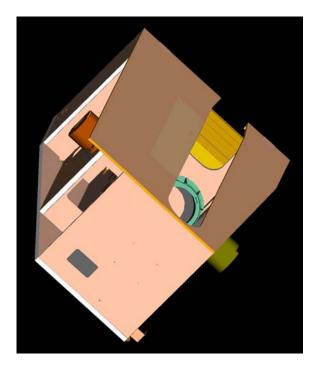




Satellite Position: 5 minutes Prior to Max Solar Exposure

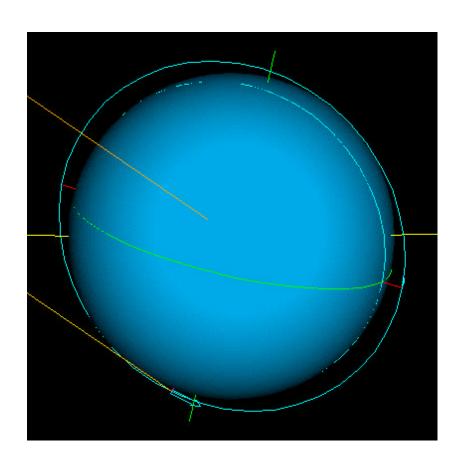


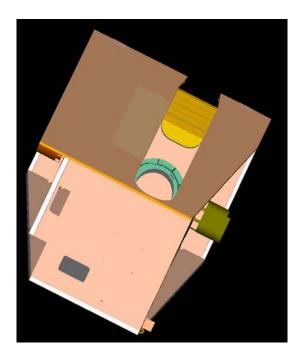




Satellite Position: During Max Solar Exposure





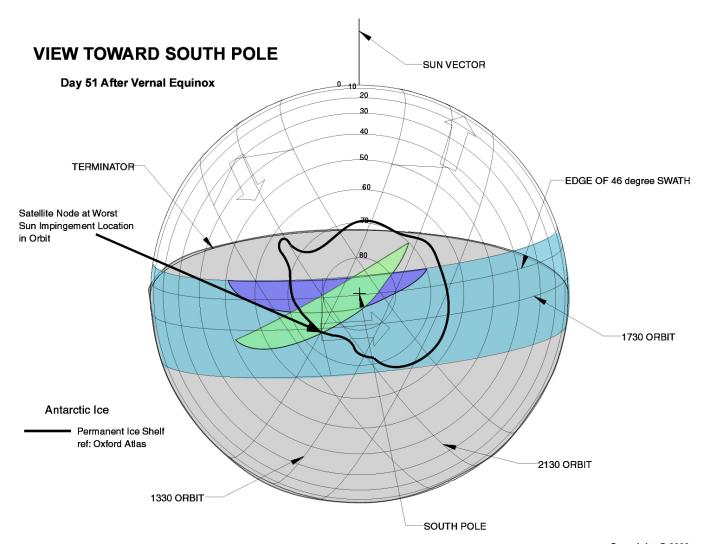


Sensor Provides Optimum Coverage in Terminator Orbits



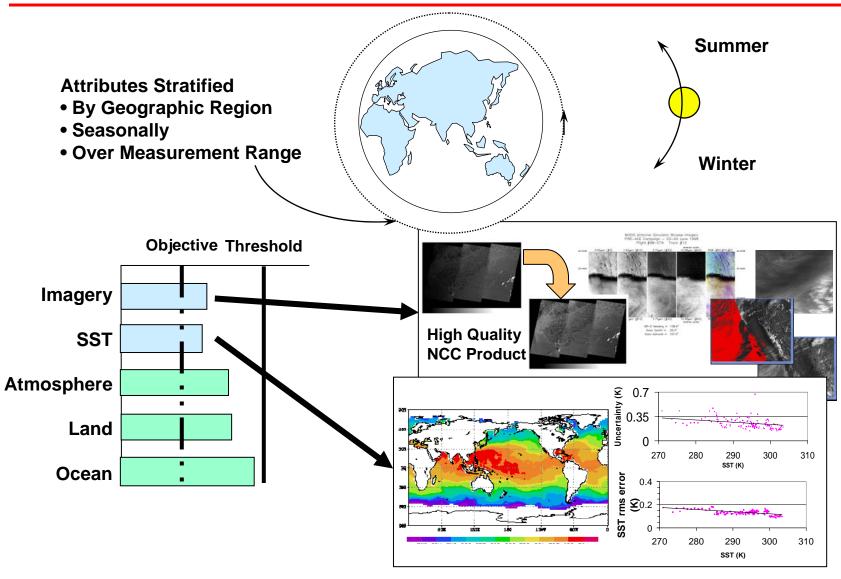
Baffled telescope has low sensitivity to far field glare and solar impingement

Data available from preceding orbit and/or Sensors in midday orbits can fill-in gap



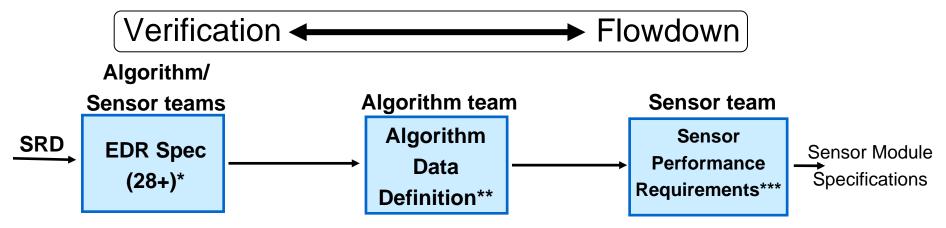
EDR Performance Optimized Over Environmental Conditions





Iterative Process to Verified System/Subsystem Specification





- HCS/HRI/VCS/VRI
- Hor/Vert Coverage
- Measurement Range
- Meas Accy/Prec/Unc
- Long-term Stability
- Mapping Uncertainty
- Min Swath Width
 - *VIIRS System
 Specification
 *System Verification
 and Validation Plan

- Bands CW/BW & Tolerances
- Bandpass Shape
- Dynamic Range/Sensitivity
- Rdmtrc Accuracy/Stability
- Horznti Smplg Interval (HSI)
- Spatial Resolution (MTF)
- Band Co-Registration
- Polarization
- Geolocation
- Auxiliary/Ancillary Data
- **Algorithm Data Definition (ADD)
 Documents (Y2371-- Y2384)

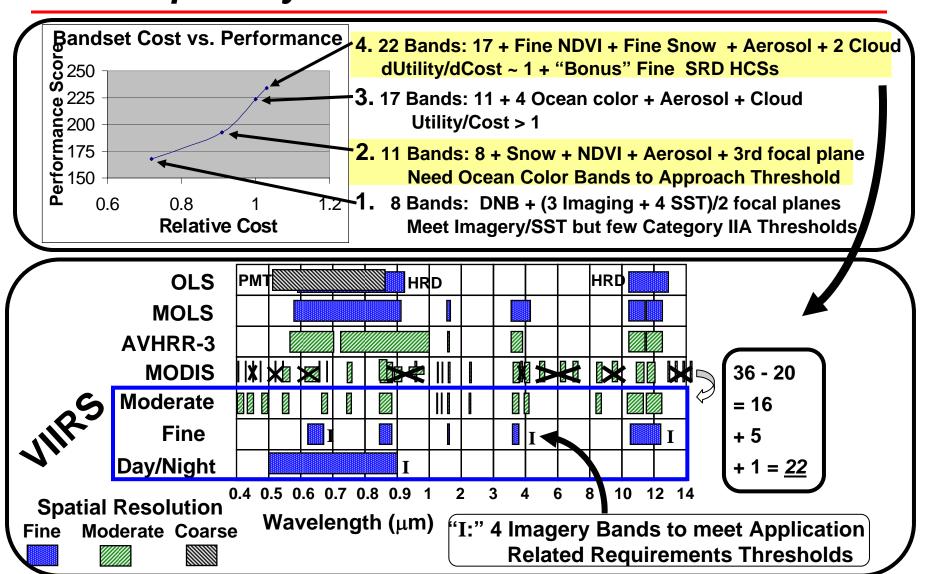
- Scan Definition
- Calibration Definition
- IFOV/Response Uniformity
- Crosstalk
- Stray Light Rejection
- LOS Pointing/Jitter Rgmnts
- CW/BW tolerance
- Spectral Uniformity
- Out-of-Band Rejection

***Performance and Specification

Verification Report

Robust Spectral Capability with Science Bonus





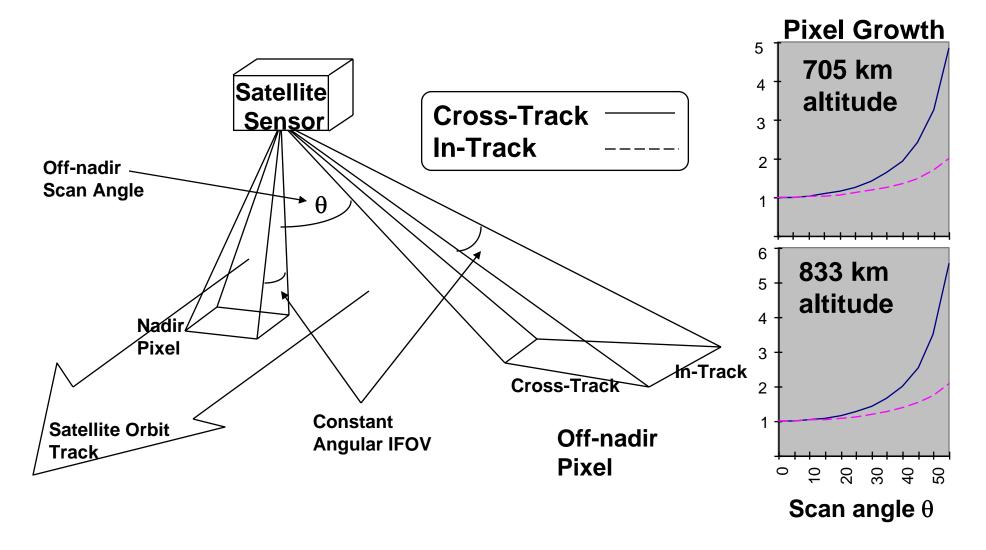
Spectral, Spatial, & Radiometric Attributes of 22 VIIRS Bands



		Band No.	Wave- length	Horiz Sample Interval (km Downtrack x Crosstrack)		Driving EDRs	Radi- ance Range	Ltyp or Ttyp	Signal to Noise Ratio (dimensionless) or NE∆T (Kelvins)		
ا			(μm)	Nadir	End of Scan				Required	Predicted	Margin
	Silicon PIN Diodes	M1	0.412	0.742 x 0.259	1.60 x 1.58	Ocean Color	Low	44.9	352	441	25%
						Aerosols	High	155	316	807	155%
VIS/NIR FPA		M2	0.445	0.742 x 0.259	1.60 x 1.58	Ocean Color	Low	40	380	524	38%
						Aerosols	High	146	409	926	126%
		M3	0.488	0.742 x 0.259	1.60 x 1.58	Ocean Color	Low	32	416	542	30%
						Aerosols	High	123	414	730	76%
		M4	0.555	0.742 x 0.259	1.60 x 1.58	Ocean Color	Low	21	362	455	26%
						Aerosols	High	90	315	638	102%
		l1	0.640	0.371 x 0.387	0.80 x 0.789	Imagery	Single	22	119	146	23%
	<u>i</u>	M5	0.672	0.742 x 0.259	1.60 x 1.58	Ocean Color	Low	10	242	298	23%
	Si					Aerosols	High	68	360	522	45%
		M6	0.746	0.742 x 0.776	1.60 x 1.58	Atmospheric Corr'n	Single	9.6	199	239	20%
		12	0.865	0.371 x 0.387	0.80 x 0.789	NDVI	Single	25	150	225	50%
		M7	0.865	0.742 x 0.259	1.60 x 1.58	Ocean Color	Low	6.4	215	388	81%
						Aerosols	High	33.4	340	494	45%
CC	CD	DNB	0.7	0.742 x 0.742	0.742 x 0.742	Imagery	Var.	6.70E-05	6	5.7	-5%
S/MWIR	gCdTe (HCT)	M8	1.24	0.742 x 0.776	1.60 x 1.58	Cloud Particle Size	Single	5.4	74	98	32%
		M9	1.378	0.742 x 0.776	1.60 x 1.58	Cirrus/Cloud Cover	Single	6	83	155	88%
		13	1.61	0.371 x 0.387	0.80 x 0.789	Binary Snow Map	Single	7.3	6.0	97	1523%
		M10	1.61	0.742 x 0.776	1.60 x 1.58	Snow Fraction	Single	7.3	342	439	28%
	Ę	M11	2.25	0.742 x 0.776	1.60 x 1.58	Clouds	Single	0.12	10	17	66%
	Ğ	14	3.74	0.371 x 0.387	0.80 x 0.789	Imagery Clouds	Single	270 K	2.500	0.486	415%
	エ	M12	3.70	0.742 x 0.776	1.60 x 1.58	SST	Single	270 K	0.396	0.218	82%
	P	M13	4.05	0.742 x 0.259	1.60 x 1.58	SST	Low	300 K	0.107	0.063	69%
						Fires	High	380 K	0.423	0.334	27%
LWIR		M14	8.55	0.742 x 0.776	1.60 x 1.58	Cloud Top Properties	Single	270 K	0.091	0.075	22%
	HCT	M15	10.763	0.742 x 0.776	1.60 x 1.58	SST	Single	300 K	0.091	0.075	85%
		15	11.450	0.371 x 0.387	0.80 x 0.789	Cloud Imagery	Single	210 K	1.500	0.789	90%
	Ъ	M16	12.013	0.742 x 0.776	1.60 x 1.58	SST	Single	300 K	0.072	0.769	42%

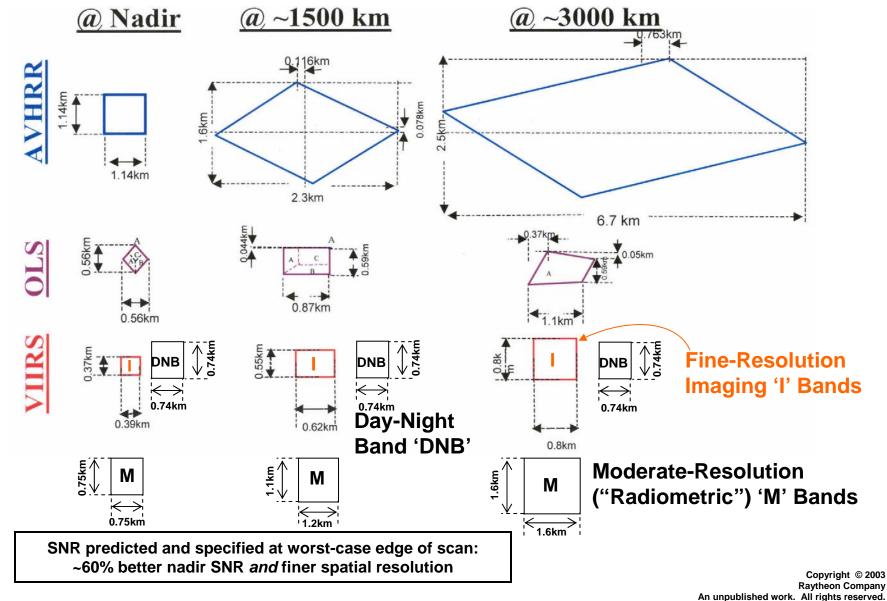
Nadir to Edge of Scan Pixel Growth





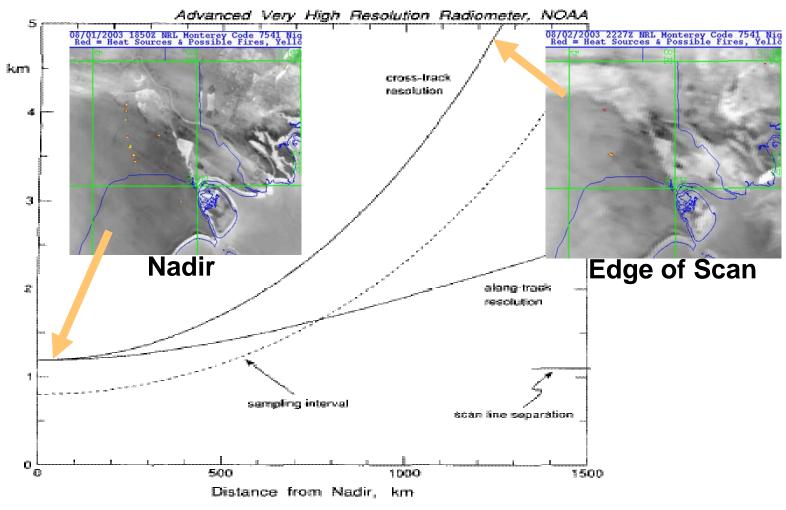
Finer Sampling, Spatial Resolution & Better Sensitivity





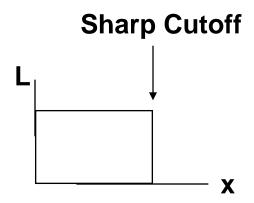
AVHRR Scan Geometry: Nadir & Edge of Scan

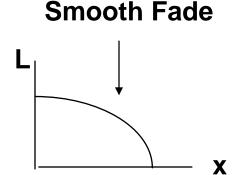




Spatial Frequency Concept: Powerful, Practical Design Tool







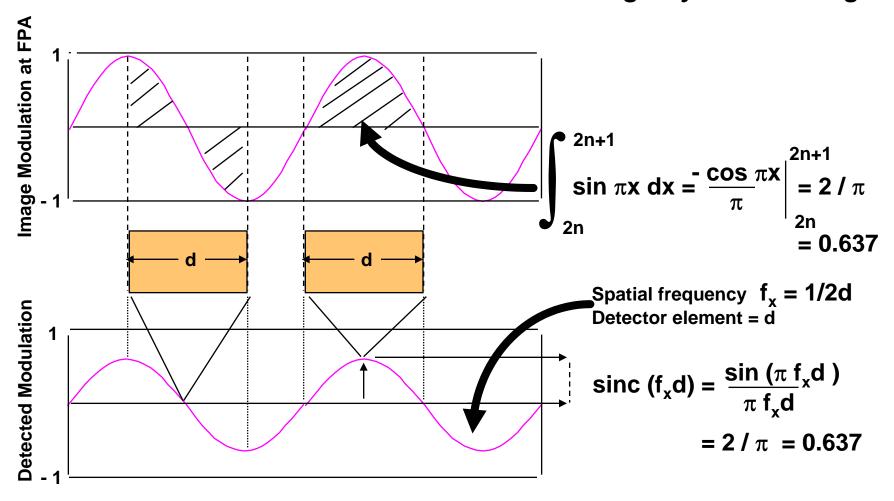
- Sharp Cutoff More Difficult to Reproduce Than Smooth Fade
- Smooth Fade Does Not Contain "High Spatial Frequency" Intensity Variations - Less Affected by System Blur
- •Any Function Can Be Represented by a Linear Summation of Pure Sinusoids
- •The Smooth Fade *Contains* Fewer High Frequency Sinusoids Than the Sharp Cutoff

Sine Wave Response is Modulation Transfer Function (MTF)



Santa Barbara Remote Sensing

Transfer of Scene Sine-Wave Modulation through System to Image

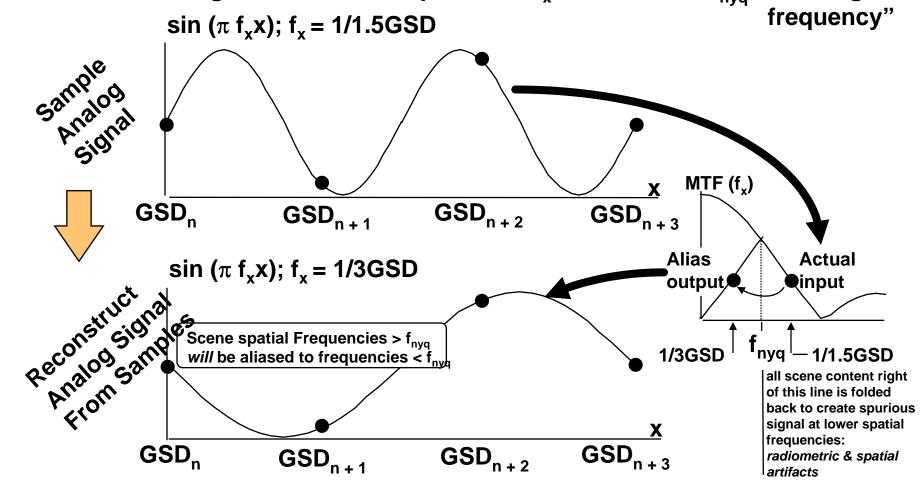


Sampling Causes "Aliasing" Error



• GSD defines "Nyquist Sampling Rate" $f_x = f_{nyq} = 1/2GSD$

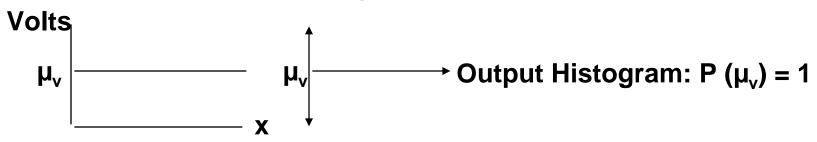




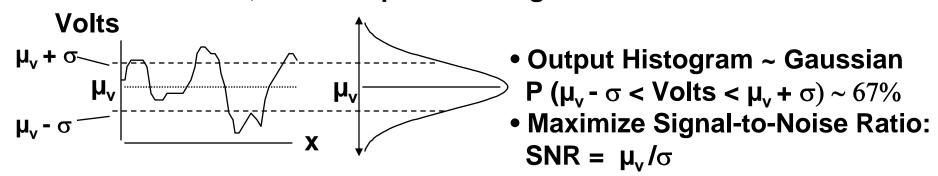
Radiometric Resolution is Limited by Noise



- Consider Sensor Response to a Constant Radiance Input
- If We Could Obtain a Signal Like This:

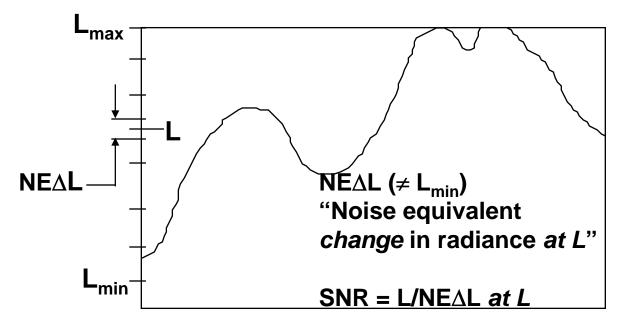


- Then Radiometric sensitivity would be unlimited
- Of course, that is impossible. Signal is more like this:



Signal to Noise Ratio = L/NE∆L

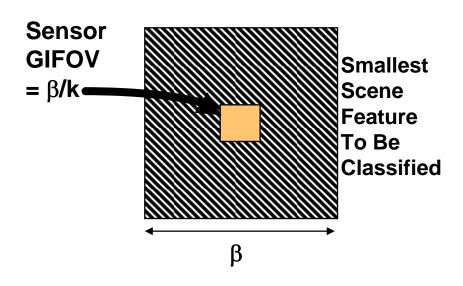




Distance across track

Design Challenge: Optimize MTF & SNR to Features

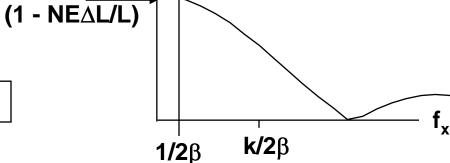




Want smallest k (largest GIFOV) to match SNR (L/NE \triangle L):

- 1. Radiometric Precision Error (NE Δ L/L) ~ Allowable MTF Reduction at f_x = 1/2 β
- 2. Select k so that sensor MTF > allowable value at $f_x = 1/2\beta$

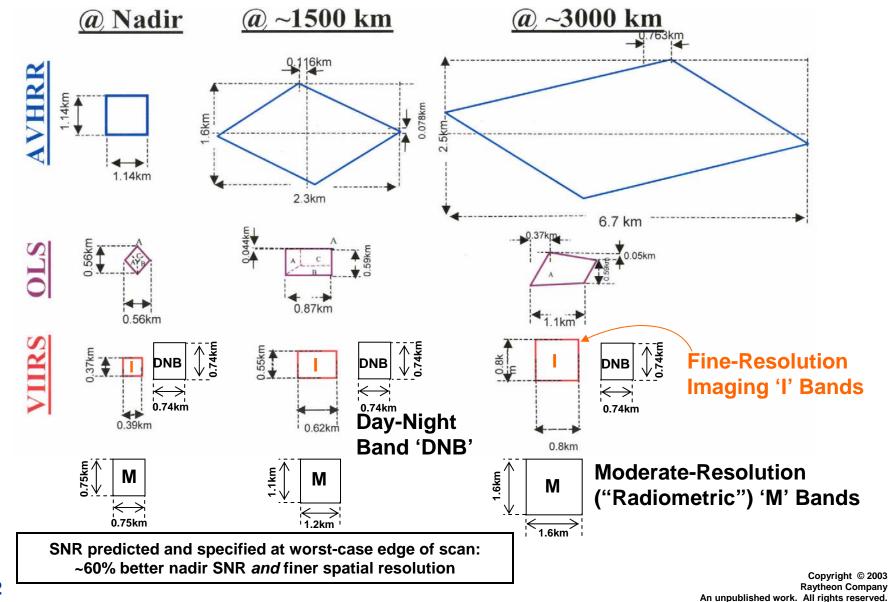
MTF (f_x)



Want Small GIFOV and High SNR

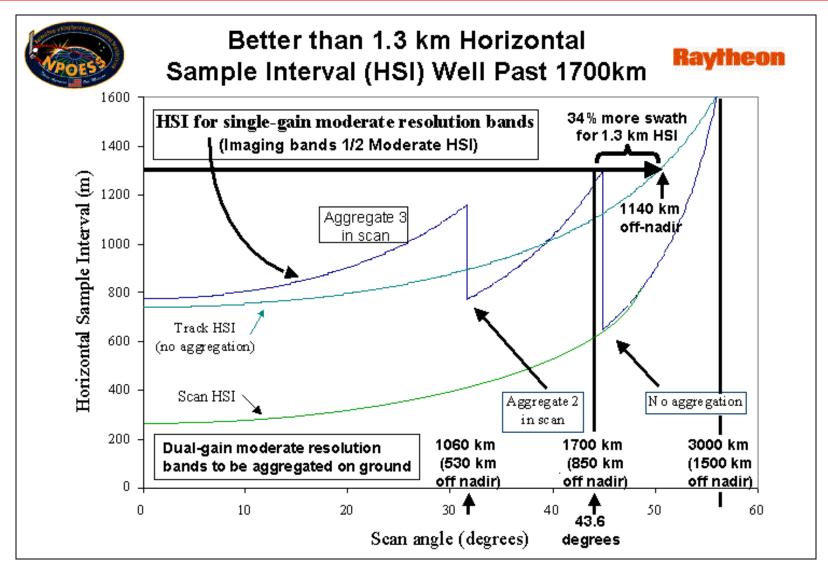
Finer Sampling, Spatial Resolution & Better Sensitivity





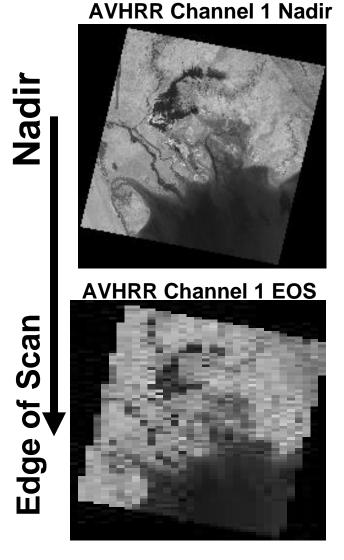
VIIRS Scan Geometry: How will image look nadir vs. Edge?

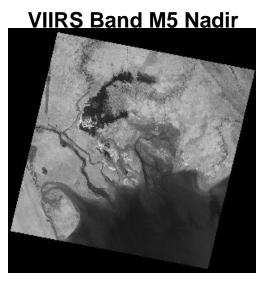


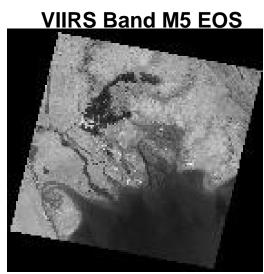


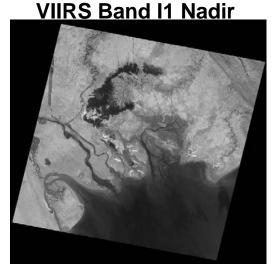
VIIRS Dramatically Improves Edge-of-Scan (EOS) Imagery

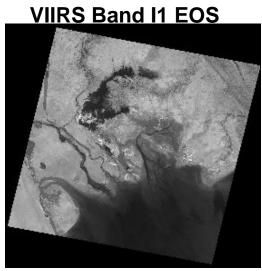












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